## Parameterized and Approximation Algorithms for the <br> Maximum Bimodal Subgraph Problem

## GD 2023, Palermo

Walter Fedor V. Petr A. Tanmay Stephen M. Diana Didimo $^{1}$ Fomin ${ }^{2}$ Golovach ${ }^{2}$ Inamdar ${ }^{2}$ Kobourov ${ }^{3}$ Sieper ${ }^{4}$

${ }^{1}$ University of Perugia, Italy<br>${ }^{2}$ University of Bergen, Norway

${ }^{3}$ University of Arizona, USA<br>${ }^{4}$ University of Würzburg, Germany

## Bimodality



## Bimodality



## Bimodality



Bimodal vertex: All outgoing (incoming) edges are consecutive.

## Bimodality



Bimodal vertex: All outgoing (incoming) edges are consecutive.
Bimodal Graph: Every vertex is bimodal.

## Bimodality



Bimodal vertex: All outgoing (incoming) edges are consecutive.
Bimodal Graph: Every vertex is bimodal.

## Bimodality



Bimodal vertex: All outgoing (incoming) edges are consecutive.
Bimodal Graph: Every vertex is bimodal.

## Bimodality



Embedding important!
$\rightarrow$ assume plane graphs

Bimodal vertex: All outgoing (incoming) edges are consecutive.
Bimodal Graph: Every vertex is bimodal.

## Bimodality



Bimodal vertex: All outgoing (incoming) edges are consecutive.
Bimodal Graph: Every vertex is bimodal.

Embedding important!
$\rightarrow$ assume plane graphs

## Motivation:

Necessary criterion for Upward Planarity, Level Planarity, ...

## Bimodality



Bimodal vertex: All outgoing (incoming) edges are consecutive.
Bimodal Graph: Every vertex is bimodal.

Embedding important!
$\rightarrow$ assume plane graphs

## Motivation:

Necessary criterion for Upward Planarity, Level Planarity, ...
Sufficient criterion for L-Drawings.

## Maximum Bimodal Subgraph Problem (MBS)

Given: Plane directed graph G

## Maximum Bimodal Subgraph Problem (MBS)

## Given: Plane directed graph G

Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum number of edges among all bimodal subgraphs of $G$.

## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.

## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of eciges among all bimodal subgraphs of $G$.


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation)
for MBS
- Branch-and-Bound

Algorithm for MBS

# Maximum Weighted Bimodal Subgraph Problem (MWBS) 

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
■ Branch-and-Bound
Algorithm for MBS

Our Contribution:

# Maximum Weighted Bimodal Subgraph Problem (MWBS) 

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of eciges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:

- Parameter: Branchwidth (/Treewidth)


# Maximum Weighted Bimodal Subgraph Problem (MWBS) 

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of edyes among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:

- Parameter: Branchwidth (/Treewidth)
- FPT-Algorithm: running time $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of eciges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:

- Parameter: Branchwidth (/Treewidth)
- FPT-Algorithm: running time $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$
- Parameter: Number $b$ of non-bimodal vertices


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of edyes among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:

- Parameter: Branchwidth (/Treewidth)
- FPT-Algorithm: running time $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$
- Parameter: Number $b$ of non-bimodal vertices
- FPT-Algorithm: running time $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of euges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:

- Parameter: Branchwidth (/Treewidth)
- FPT-Algorithm: running time $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$
- Parameter: Number $b$ of non-bimodal vertices
- FPT-Algorithm: running time $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$
- Compression to kernel of size polynomial in $b$


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of exiges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:

- Parameter: Branchwidth (/Treewidth)
- FPT-Algorithm: running time $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$
- Parameter: Number $b$ of non-bimodal vertices
- FPT-Algorithm: running time $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$
$\square$ Compression to kernel of size polynomial in $b$
E EPTAS for MWBS and for the corresponding minimization variant.


## Maximum Weighted Bimodal Subgraph Problem (MWBS)

Given: Plane directed graph $G$ with rational edge weights
Wanted: Subgraph $G^{\prime}$ of $G$ such that $G^{\prime}$ is bimodal and has the maximum weight number of exiges among all bimodal subgraphs of $G$.

Previous Results:
[Binucci, Didimo, Giordano 2008]

- M(W)BS is NP-hard
- Heuristic
(2-Approximation) for MBS
- Branch-and-Bound Algorithm for MBS

Our Contribution:
In this talk:

- Parameter: Branchwidth (/Treewidth)
- FPT-Algorithm: running time $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$
- Parameter: Number $b$ of non-bimodal vertices
- FPT-Algorithm: running time $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$
- Compression to kernel of size polynomial in $b$
- EPTAS for MWBS and for the corresponding minimization variant.


## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.

## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


Each edge $a$ in $T$ splits $T$ into two connected components and corresponds to the set of vertices in $G$ that are adjacent to edges from both components, the middle set of $a$.

## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


Each edge $a$ in $T$ splits $T$ into two connected components and corresponds to the set of vertices in $G$ that are adjacent to edges from both components, the middle set of $a$.

## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


Each edge $a$ in $T$ splits $T$ into two connected components and corresponds to the set of vertices in $G$ that are adjacent to edges from both components, the middle set of $a$.
The width of $T$ is the maximum size of a middle set of $T$.

## Branchwidth

Let $G$ be a graph. A branch decomposition of $G$ is an unrooted proper binary tree $T$ whose leaves correspond bijectively to $E(G)$.


Each edge $a$ in $T$ splits $T$ into two connected components and corresponds to the set of vertices in $G$ that are adjacent to edges from both components, the middle set of $a$.
The width of $T$ is the maximum size of a middle set of $T$.
$(2,3)$ The branchwidth $\operatorname{bw}(G)$ of $G$ is the minimum width of all branch decompositions of $G$.

## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


- intersects $G$ only at the middle set of $a$


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


- intersects $G$ only at the middle set of $a$
- separates the edges in the two components of $T$
- traverses each face of $G$ at most once


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :



- intersects $G$ only at the middle set of $a$
- separates the edges in the two components of $T$
- traverses each face of $G$ at most once


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


- intersects $G$ only at the middle set of $a$
- separates the edges in the two components of $T$
- traverses each face of $G$ at most once


## Sphere-Cut Decomposition

Let $G$ be a connected planar graph embedded in the sphere. A Sphere-Cut Decomposition of $G$ is a branch decomposition $T$ together with simple closed curves $\phi_{a}$ for every edge $a \in T$, such that $\phi_{a}$ :


- traverses each face of $G$ at most once


## Parametrization by Branchwidth

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:

$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.

## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:

$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.

- If $v$ is cut by a curve $\phi$ : keep track on which sides of $\phi$ the switches are.


## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(b w(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:

$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.

- If $v$ is cut by a curve $\phi$ : keep track on which sides of $\phi$ the switches are.
■ Encode switches as configurations by the cw order of in- and outgoing edges.


## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:

$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.

- If $v$ is cut by a curve $\phi$ : keep track on which sides of $\phi$ the switches are.
■ Encode switches as configurations by the cw order of in- and outgoing edges.


## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(b w(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:


$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.

- If $v$ is cut by a curve $\phi$ : keep track on which sides of $\phi$ the switches are.
- Encode switches as configurations by the cw order of in- and outgoing edges.


## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:

$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.
■ If $v$ is cut by a curve $\phi$ : keep track on which sides of $\phi$ the switches are.
■ Encode switches as configurations by the cw order of in- and outgoing edges.
$\square$ If $v$ is bimodal, there are 6 possible configurations: (o), (i), (o, i), (i, o), (o, i, o), (i, o, i)

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:

$\square v$ is bimodal $\Leftrightarrow$ at most one switch from incoming to outgoing edges and vice versa in the clockwise order of the edges incident to $v$.

- If $v$ is cut by a curve $\phi$ : keep track on which sides of $\phi$ the switches are.
- Encode switches as configurations by the cw order of in- and outgoing edges.
■ If $v$ is bimodal, there are 6 possible configurations: (o), (i), (o, i), (i, o), (o, i, o), (i, o, i)
$\square$ Not unique:. E.g. (o) implies (i, o), (o, i), ...


## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:


- A configuration set $\mathcal{X}$ for $\phi$ is a set with a configuration $X_{v}$ for every vertex $v$ cut by $\phi$.


## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:



- A configuration set $\mathcal{X}$ for $\phi$ is a set with a configuration $X_{v}$ for every vertex $v$ cut by $\phi$.
- $G$ has configuration set $\mathcal{X}$, if every $v$ cut by $\phi$ is of configuration $X_{v}$ in $\phi$.


## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:



- A configuration set $\mathcal{X}$ for $\phi$ is a set with a configuration $X_{v}$ for every vertex $v$ cut by $\phi$.

■ $G$ has configuration set $\mathcal{X}$, if every $v$ cut by $\phi$ is of configuration $X_{v}$ in $\phi$.

■ If $\phi$ corresponds to an edge of $T$ in an sphere-cut decomposition, it cuts at most $\mathrm{bw}(G)$ vertices.

## Parametrization by Branchwidth: Configurations

## Theorem 1: <br> There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:



- A configuration set $\mathcal{X}$ for $\phi$ is a set with a configuration $X_{v}$ for every vertex $v$ cut by $\phi$.

■ $G$ has configuration set $\mathcal{X}$, if every $v$ cut by $\phi$ is of configuration $X_{v}$ in $\phi$.

■ If $\phi$ corresponds to an edge of $T$ in an sphere-cut decomposition, it cuts at most bw $(G)$ vertices.
$\rightarrow$ There exist at most $6^{\mathrm{bw}(G)}$ configuration sets for $\phi$.

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

- Two configurations $X, X^{\prime}$ are compatible, if their concatenation - after deleting consecutive duplicates - is a substring of ( $\mathrm{o}, \mathrm{i}, \mathrm{o}$ ) or ( $\mathrm{i}, \mathrm{o}, \mathrm{i}$ ).


## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.
Idea:
■ Two configurations $X, X^{\prime}$ are compatible, if their concatenation - after deleting consecutive duplicates - is a substring of ( $\mathrm{o}, \mathrm{i}, \mathrm{o}$ ) or ( $\mathrm{i}, \mathrm{o}, \mathrm{i}$ ).

$$
(\mathrm{i}, \mathrm{o}, \mathrm{i}),(\mathrm{i}) \quad \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}, \mathrm{i}) \quad \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i})
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.
Idea:
■ Two configurations $X, X^{\prime}$ are compatible, if their concatenation - after deleting consecutive duplicates - is a substring of ( $\mathrm{o}, \mathrm{i}, \mathrm{o}$ ) or ( $\mathrm{i}, \mathrm{o}, \mathrm{i}$ ).

$$
(\mathrm{i}, \mathrm{o}, \mathrm{i}),(\mathrm{i}) \quad \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}, \mathrm{i}) \quad \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}) \quad \text { compatible }
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.
Idea:
■ Two configurations $X, X^{\prime}$ are compatible, if their concatenation - after deleting consecutive duplicates - is a substring of ( $\mathrm{o}, \mathrm{i}, \mathrm{o}$ ) or ( $\mathrm{i}, \mathrm{o}, \mathrm{i}$ ).

$$
\begin{array}{llll}
(\mathrm{i}, \mathrm{o}, \mathrm{i}),(\mathrm{i}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}, \mathrm{i}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}) & \text { compatible } \\
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{o}) & \rightarrow(\mathrm{i}, \mathrm{o}) & \text { compatible }
\end{array}
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

■ Two configurations $X, X^{\prime}$ are compatible, if their concatenation - after deleting consecutive duplicates - is a substring of ( $\mathrm{o}, \mathrm{i}, \mathrm{o}$ ) or ( $\mathrm{i}, \mathrm{o}, \mathrm{i}$ ).

$$
\begin{array}{llll}
(\mathrm{i}, \mathrm{o}, \mathrm{i}),(\mathrm{i}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}, \mathrm{i}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}) & \text { compatible } \\
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{o}) & \rightarrow(\mathrm{i}, \mathrm{o}) & \text { compatible } \\
(\mathrm{o}, \mathrm{i}),(\mathrm{i}, \mathrm{o}, \mathrm{i}) & \rightarrow(\mathrm{o}, \mathrm{i}, \mathrm{i}, \mathrm{o}, \mathrm{i}) & \rightarrow(\mathrm{o}, \mathrm{i}, \mathrm{o}, \mathrm{i}) & \text { not compatible }
\end{array}
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Idea:


■ Two configurations $X, X^{\prime}$ are compatible, if their concatenation - after deleting consecutive duplicates - is a substring of ( $\mathrm{o}, \mathrm{i}, \mathrm{o}$ ) or ( $\mathrm{i}, \mathrm{o}, \mathrm{i}$ ).

$$
\begin{array}{llll}
(\mathrm{i}, \mathrm{o}, \mathrm{i}),(\mathrm{i}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}, \mathrm{i}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{i}) & \text { compatible } \\
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) & \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{o}) & \rightarrow(\mathrm{i}, \mathrm{o}) & \text { compatible } \\
(\mathrm{o}, \mathrm{i}),(\mathrm{i}, \mathrm{o}, \mathrm{i}) & \rightarrow(\mathrm{o}, \mathrm{i}, \mathrm{i}, \mathrm{o}, \mathrm{i}) & \rightarrow(\mathrm{o}, \mathrm{i}, \mathrm{o}, \mathrm{i}) & \text { not compatible }
\end{array}
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

- Two configurations $X, X^{\prime}$ are compatible with respect to a configuration $X^{*}$, if their concatenation - after deleting consecutive duplicates - is a substring of $X^{*}$.


## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

- Two configurations $X, X^{\prime}$ are compatible with respect to a configuration $X^{*}$, if their concatenation - after deleting consecutive duplicates - is a substring of $X^{*}$.

$$
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) \rightarrow(\mathrm{i}, \mathrm{o}, \mathrm{o}) \quad \rightarrow \quad(\mathrm{i}, \mathrm{o}) \quad \begin{aligned}
& \text { compatible } \\
& \text { with }(\mathrm{o}, \mathrm{i}, \mathrm{o})
\end{aligned}
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

- Two configurations $X, X^{\prime}$ are compatible with respect to a configuration $X^{*}$, if their concatenation - after deleting consecutive duplicates - is a substring of $X^{*}$.

$$
\begin{aligned}
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) \rightarrow \quad(\mathrm{i}, \mathrm{o}, \mathrm{o}) \quad \rightarrow \quad(\mathrm{i}, \mathrm{o}) \quad \begin{array}{l}
\text { compatible } \\
\\
\\
\\
\\
\\
\\
\\
\text { with not not compatible } \\
\\
\text { with }(\mathrm{o}, \mathrm{i})
\end{array}
\end{aligned}
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

- Two configurations $X, X^{\prime}$ are compatible with respect to a configuration $X^{*}$, if their concatenation - after deleting consecutive duplicates - is a substring of $X^{*}$.

$$
\begin{aligned}
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) \rightarrow \quad(\mathrm{i}, \mathrm{o}, \mathrm{o}) \rightarrow(\mathrm{i}, \mathrm{o}) \quad \begin{array}{l}
\text { compatible } \\
\text { with }(\mathrm{o}, \mathrm{i}, \mathrm{o}) \\
\text { but not compatible } \\
\text { witho }(\mathrm{o}, \mathrm{i})
\end{array}
\end{aligned}
$$

## Parametrization by Branchwidth: Configurations

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Idea:

■ Two configurations $X, X^{\prime}$ are compatible with respect to a configuration $X^{*}$, if their concatenation - after deleting consecutive duplicates - is a substring of $X^{*}$.

$$
\begin{aligned}
(\mathrm{i}, \mathrm{o}),(\mathrm{o}) \rightarrow \quad(\mathrm{i}, \mathrm{o}, \mathrm{o}) \rightarrow \quad(\mathrm{i}, \mathrm{o}) \quad \begin{array}{l}
\text { compatible } \\
\\
\\
\\
\\
\\
\\
\\
\text { with not compation }(\mathrm{o}) \\
\text { with }(\mathrm{o}, \mathrm{i})
\end{array}
\end{aligned}
$$

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

- Compute an optimal Sphere-Cut Decomposition $T$, root $T$ arbitrarily at a leaf $r$.


## G



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

■ Compute an optimal Sphere-Cut Decomposition $T$, root $T$ arbitrarily at a leaf $r$.

- Let the inside of a curve be the side not containing $r$



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

- Compute an optimal Sphere-Cut Decomposition $T$, root $T$ arbitrarily at a leaf $r$.
- Let the inside of a curve be the side not containing $r$
- Compute bottom up for every curve $\phi_{a}$ and every configuration set $\mathcal{X}$ for $\phi_{a}$ the maximum subgraph of $G$ that is bimodal in $\phi_{a}$ and has $\mathcal{X}$ in $\phi_{a}$.



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

- Compute an optimal Sphere-Cut Decomposition $T$, root $T$ arbitrarily at a leaf $r$.

■ Let the inside of a curve be the side not containing $r$

- Compute bottom up for every curve $\phi_{a}$ and every configuration set $\mathcal{X}$ for $\phi_{a}$ the maximum subgraph of $G$ that is bimodal in $\phi_{a}$ and has $\mathcal{X}$ in $\phi_{a}$.



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

- Compute an optimal Sphere-Cut Decomposition $T$, root $T$ arbitrarily at a leaf $r$.

■ Let the inside of a curve be the side not containing $r$

- Compute bottom up for every curve $\phi_{a}$ and every configuration set $\mathcal{X}$ for $\phi_{a}$ the maximum subgraph of $G$ that is bimodal in $\phi_{a}$ and has $\mathcal{X}$ in $\phi_{a}$.



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\operatorname{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

- Base Case: The curve $\phi$ contains a single edge $e=\left(v, v^{\prime}\right)$.



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

- Inductive Step: edges in $\phi$ are partitioned by $\phi_{1}, \phi_{2}$



## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

.. Inductive Step: edges in $\phi$ are partitioned by $\phi_{1}, \phi_{2}$


Iterate through every combination of configuration sets $\mathcal{X}, \mathcal{X}_{1}, \mathcal{X}_{2}$ for the curve $\phi, \phi_{1}, \phi_{2}$.

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

■ Inductive Step: edges in $\phi$ are partitioned by $\phi_{1}, \phi_{2}$


Test for every vertex $v$ that is cut by at least one of $\phi, \phi_{1}, \phi_{2}$ :

■ If $v$ is cut by $\phi_{1}$ and $\phi_{2}$, but not $\phi$ : Are $X_{v, 1}, X_{v, 2}$ compatible?

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

.■ Inductive Step: edges in $\phi$ are partitioned by $\phi_{1}, \phi_{2}$


Test for every vertex $v$ that is cut by at least one of $\phi, \phi_{1}, \phi_{2}$ :
$\square$ If $v$ is cut by $\phi$ and only one of $\phi_{1}, \phi_{2}$ :
Is $X_{v, 1}$ (or $X_{v, 2}$ ) a substring of $X_{v}$ ?

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

.■ Inductive Step: edges in $\phi$ are partitioned by $\phi_{1}, \phi_{2}$


Test for every vertex $v$ that is cut by at least one of $\phi, \phi_{1}, \phi_{2}$ :
$\square$ If $v$ is cut by all three of $\phi, \phi_{1}, \phi_{2}$ :
Are $\mathcal{X}_{v, 2}$ and $\mathcal{X}_{v, 1}$ compatible with respect to $\mathcal{X}_{v}$ ?

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

.. Inductive Step: edges in $\phi$ are partitioned by $\phi_{1}, \phi_{2}$


Runtime for one step:

$$
\mathcal{O}\left(6^{3 \cdot \mathrm{bw}(G)}\right) \cdot n^{\mathcal{O}(1)}=2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}
$$

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

■ Final Step: only root-edge left

## Parametrization by Branchwidth: Proof Sketch

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Proof sketch:

■ Final Step: only root-edge left


## Parametrization by Branchwidth

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

## Parametrization by Branchwidth

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.
Since $\operatorname{bw}(G)-1 \leq \operatorname{tw}(G) \leq\left\lfloor\frac{3}{2} \operatorname{bw}(G)\right\rfloor-1$ :
[Robertson and Seymour, 1991]

## Parametrization by Branchwidth

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Since $\operatorname{bw}(G)-1 \leq \operatorname{tw}(G) \leq\left\lfloor\frac{3}{2} \operatorname{bw}(G)\right\rfloor-1: \quad$ [Robertson and Seymour, 1991]

## Corollary 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\operatorname{tw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by treewidth.

## Parametrization by Branchwidth

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Since $\operatorname{bw}(G)-1 \leq \operatorname{tw}(G) \leq\left\lfloor\frac{3}{2} \mathrm{bw}(G)\right\rfloor-1$ :
[Robertson and Seymour, 1991]

## Corollary 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\operatorname{tw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by treewidth.

Since the treewidth of a planar graph with $n$ vertices is bounded in $\mathcal{O}(\sqrt{n})$ :

## Parametrization by Branchwidth

## Theorem 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\mathrm{bw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by branchwidth.

Since $\operatorname{bw}(G)-1 \leq \operatorname{tw}(G) \leq\left\lfloor\frac{3}{2} b w(G)\right\rfloor-1$ :
[Robertson and Seymour, 1991]

## Corollary 1:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\operatorname{tw}(G))} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by treewidth.

Since the treewidth of a planar graph with $n$ vertices is bounded in $\mathcal{O}(\sqrt{n})$ :

## Corollary 2:

There is an algorithm that solves MWBS in $2^{\mathcal{O}(\sqrt{n})}$ time.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

# Parametrization by the Number of Non-Bimodal Vertices 

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch:

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

Proof sketch: Consider the decision version of MWBS with target value $W$.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

Proof sketch: Consider the decision version of MWBS with target value $W$.
Reduction Rule 1: Delete isolated vertices.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch: Consider the decision version of MWBS with target value $W$.

Reduction Rule 1: Delete isolated vertices.
Reduction Rule 2: Delete an edge $e$ that is incident to two bimodal vertices. Reduce $W$ to $W-w(e)$.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch: Consider the decision version of MWBS with target value $W$.

Reduction Rule 1: Delete isolated vertices.
Reduction Rule 2: Delete an edge $e$ that is incident to two bimodal vertices. Reduce $W$ to $W-w(e)$.
Reduction Rule 3: Replace bimodal vertices of degree $>1$ with one vertex of degree 1 per incident edge.

$\rightarrow$


## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch: Consider the decision version of MWBS with target value $W$.

Reduction Rule 1: Delete isolated vertices.
Reduction Rule 2: Delete an edge $e$ that is incident to two bimodal vertices. Reduce $W$ to $W-w(e)$.
Reduction Rule 3: Replace bimodal vertices of degree $>1$ with one vertex of degree 1 per incident edge.
$\rightarrow$ At most $b$ vertices with degree $\geq 2$.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

Proof sketch: Consider the decision version of MWBS with target value $W$. $G^{\prime}$ has treewidth bounded in $\mathcal{O}(\sqrt{b})$.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

Proof sketch: Consider the decision version of MWBS with target value $W$.
$G^{\prime}$ has treewidth bounded in $\mathcal{O}(\sqrt{b})$.
$\rightarrow$ Use the algorithm from Theorem 1.

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch: Consider the decision version of MWBS with target value $W$.

$G^{\prime}$ has treewidth bounded in $\mathcal{O}(\sqrt{b})$.
$\rightarrow$ Use the algorithm from Theorem 1.
Running time:

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

Proof sketch: Consider the decision version of MWBS with target value $W$. $G^{\prime}$ has treewidth bounded in $\mathcal{O}(\sqrt{b})$.
$\rightarrow$ Use the algorithm from Theorem 1.
Running time: $\quad 2^{\mathcal{O}\left(b w\left(G^{\prime}\right)\right)} \cdot n^{\mathcal{O}(1)}$

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch: Consider the decision version of MWBS with target value $W$.

$G^{\prime}$ has treewidth bounded in $\mathcal{O}(\sqrt{b})$.
$\rightarrow$ Use the algorithm from Theorem 1.
Running time: $\quad 2^{\mathcal{O}\left(b w\left(G^{\prime}\right)\right)} \cdot n^{\mathcal{O}(1)}=2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$

## Parametrization by the Number of Non-Bimodal Vertices

## Theorem 2:

There exists an algorithm that solves MWBS with $b$ non-bimodal vertices in $2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$ time. In particular, MWBS is FPT if parameterized by $b$.

## Proof sketch: Consider the decision version of MWBS with target value $W$.

$G^{\prime}$ has treewidth bounded in $\mathcal{O}(\sqrt{b})$.
$\rightarrow$ Use the algorithm from Theorem 1.
Running time: $\quad 2^{\mathcal{O}\left(b w\left(G^{\prime}\right)\right)} \cdot n^{\mathcal{O}(1)}=2^{\mathcal{O}(\sqrt{b})} \cdot n^{\mathcal{O}(1)}$

## Open Problems

- Extend to the maximum $k$-modal subgraph problem for any given even integer $k \geq 2$.



## Open Problems

■ Extend to the maximum $k$-modal subgraph problem for any given even integer $k \geq 2$.

- Limit the number of edges that can be deleted by an integer $h$.

Possible parameters: branchwidth/treewidth; $h$


## Open Problems

■ Extend to the maximum $k$-modal subgraph problem for any given even integer $k \geq 2$.

- Limit the number of edges that can be deleted by an integer $h$. Possible parameters: branchwidth/treewidth; $h$
- Study MBS in the variable embedding setting.


